

Curving the Doubled Space: A para-Hermitian geometry for DFT

Recent Advances in T/U-dualities and Generalized Geometries

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Key Points – “Curving the Doubled Space”

- ▶ Alternative implementation of constraint
- ▶ para-Kähler and para-Hermitian geometries
- ▶ Connections for these geometries

Other and related Approaches

In the literature

- ▶ DFT on group manifolds [Blumenhagen, Haßler, Lüst]
- ▶ DFT and QP-manifolds [Heller, Ikeda, Watamura]
- ▶ Extended Riemannian Geometry and NQ-manifolds [Deser, Sämann]

Outline

Overview of GG and DFT

Restricted Fields vs. Restricted Derivatives

para-Kähler and para-Hermitian Geometries

Canonical Connections

Relation to Generalized Geometry

Overview of GG and DFT

Generalized Geometry

[Hitchin, Gualtieri]

Extended vector bundle $E = TM \oplus T^*M$

- ▶ Generalized vectors: $X = (x, \alpha) \in \Gamma(E)$
- ▶ $O(D, D)$ metric: $\eta(X, Y) = \iota_x \beta + \iota_y \alpha$
- ▶ anchor map: $\pi : E \longrightarrow TM, \pi(X) \mapsto x$

Derivative and Bracket

- ▶ Dorfman: $\mathbb{L}_X Y = ([x, y], \mathcal{L}_x \beta - \iota_y d\alpha)$ with $J = 0$
- ▶ Courant: $\llbracket X, Y \rrbracket = \mathbb{L}_X Y - \frac{1}{2} d\eta(X, Y)$
- ▶ compatible: $\mathbb{L}_X \eta = 0$ and $\pi(\mathbb{L}_X Y) = \mathcal{L}_x y$

Double Field Theory

[Siegel; Hull, Zwiebach]

Double underlying space $\mathcal{P} \cong M \times \tilde{M}$

- ▶ Doubled coordinates: $x^M = (x^\mu, \tilde{x}_\mu)$
- ▶ Generalized vectors: $X = X^\mu(\frac{\partial}{\partial x^\mu} + d\tilde{x}_\mu) + X_\mu(\frac{\partial}{\partial \tilde{x}_\mu} + dx^\mu)$

Generalized Lie derivative

- ▶ $\mathbf{L}_X Y^M = X^N \partial_N Y^M - Y^N \partial_N X^M + \eta^{MN} \eta_{PQ} \partial_N X^P Y^Q$
- ▶ Algebra does not close: $J \neq 0$
- ▶ Need constraint: $\eta^{AB} \partial_A \partial_B = 0$

GG vs DFT

Generalized Geometry

- ▶ No need for section condition
- ▶ Basespace is fixed - only $O(D, D)$ transformations on E

Double Field Theory

- ▶ T-duality changes basespace: map from M to \tilde{M}
- ▶ Section condition required

GG vs DFT

Relation between GG and DFT

- ▶ After imposing section condition: only depend on half the coordinates \rightarrow DFT reduces to GG
- ▶ But different ways of picking spacetime M : which half of \mathcal{P} is base for GG?

Need extra geometric information to relate GG to DFT

Restricted Fields vs. Restricted Derivatives

Different Approach

Consider the **metric** algebroid $(E, \eta, \pi, \mathbf{L}^\nabla)$

- ▶ Vector bundle $E = T\mathcal{P}$
- ▶ metric η and compatible connection ∇
- ▶ anchor $\pi : E \rightarrow T\mathcal{P}$
- ▶ generalized Lie derivative

$$\mathbf{L}_X^\nabla Y = \nabla_{\pi(X)} Y - \nabla_{\pi(Y)} X + \theta_\nabla(Y, X)$$

“Twist” Vector θ_∇

- ▶ Given by $\eta(Z, \theta_\nabla(Y, X)) = \eta(Y, \nabla_{\pi(Z)} X)$
- ▶ Like Y-tensor: $\theta_\nabla^A(Y, X) = Y^{AB}{}_{CD} \pi^E{}_B \nabla_E X^C Y^D$

Different Approach

For $\nabla = \partial$ and $\pi = \text{Id}$ this is the algebroid for DFT

- ▶ C-bracket: $\llbracket X, Y \rrbracket = \mathbf{L}_X^\partial Y - \frac{1}{2}d\eta(X, Y)$
- ▶ Jacobiator: $J = \eta(\theta, \theta)$

To get Jacobi identity \Rightarrow need section condition:

$$\eta_{AB}\theta^A\theta^B = 0$$

Now try different approach:
instead of restricting the fields, restrict the derivatives!

Projections & Derivatives

Projection operators on $T\mathcal{P} = L \oplus \tilde{L}$

- ▶ $P, \tilde{P} : T\mathcal{P} \rightarrow T\mathcal{P}$
- ▶ Maximally isotropic w.r.t. η : $L = \text{Im } P, \quad \tilde{L} = \text{Im } \tilde{P}$
- ▶ Important property: $\eta(P(X), Y) = \eta(X, \tilde{P}(Y))$

Projected derivative

- ▶ For any metric compatible connection ∇ : $D_X := \nabla_{P(X)}$
- ▶ Projected generalized Lie derivative

$$\mathbf{L}_X^D Y = D_X Y - D_Y X + \theta_D(Y, X)$$

Vaisman Formalism

[Vaisman '12]

For $\nabla = \partial$ and $\pi = P$ can show

- ▶ since $\theta_D \in \tilde{L} = \text{Ker } P$, i.e. $P(\theta_D) = 0$
- ▶ have $\eta(\theta_D, \theta_D) = 0$
- ▶ and $J^D = 0$

Thus $(E = T\mathcal{P}, \eta, \pi = P, \mathbf{L}^D)$ is a **Leibniz** algebroid

- ▶ The Jacobi identity holds
- ▶ The fields remain unrestricted

Restricted Fields vs. Restricted Derivatives

- ▶ Different but equivalent approach to close algebra
- ▶ Fields remain unrestricted, but \mathbf{L}^D only “sees” half the coordinate dependence
- ▶ Different solutions to section condition \Leftrightarrow different splittings of $T\mathcal{P}$

para-Hermitian Geometry

Doubled space = symplectic manifold

- ▶ extra ingredient: symplectic form ω [Hull '04; Deser, Sämann '16]
- ▶ almost para-Hermitian manifold \mathcal{P} with (η, ω) and $K := \eta^{-1}\omega$
- ▶ bi-Lagrangian structure $K: T\mathcal{P} = L \oplus \tilde{L}$

$$K|_L = +1, \quad K|_{\tilde{L}} = -1 \quad \text{with} \quad K^2 = +1$$

Two aims:

- ▶ find general / canonical connections in para-Hermitian geometry
- ▶ show how ω provides the extra geometrical information to relate GG and DFT

para-Kähler and para-Hermitian Geometries

Almost Para-Hermitian Geometry

Manifold with three compatible structures

- ▶ Almost para-complex structure K : $K^2 = +1$
- ▶ Almost symplectic structure ω : $K^T \omega K = -\omega$
- ▶ pseudo-Riemannian structure η : $\eta(X, Y) = \omega(X, K(Y))$

Almost Para-Kähler Geometry

Integrability conditions

- ▶ If ω is closed: $d\omega = 0 \Rightarrow$ Almost Para-Kähler
- ▶ If K is integrable: $N_K = 0 \Rightarrow$ Para-Hermitian
- ▶ If K is integrable and ω is closed: \Rightarrow Para-Kähler

Geometry for DFT

Bi-Lagrangian manifold \mathcal{P}

- ▶ metric algebroid structure on $T\mathcal{P} = L \oplus \tilde{L}$
- ▶ C-bracket and generalized Lie derivative
- ▶ fluxes appear in $d\omega \Rightarrow$ para-Kähler or para-Hermitian

Jacobi identity

Define Jacobiator

$$J^D(X, Y, Z, W) := \eta([\mathbf{L}_X^D, \mathbf{L}_Y^D]Z - \mathbf{L}_{\mathbf{L}_X^D Y}^D Z, W)$$

Define projected tensors

- ▶ curvature: $R_P(X, Y)Z := [D_X, D_Y]Z - D_{[P(X), P(Y)]}Z$
- ▶ torsion: $\tau_P(X, Y) := P([D_X Y - D_Y X] - [P(X), P(Y)])$
- ▶ Nijenhuis: $N_P(X, Y) := \tilde{P}([P(X), P(Y)])$

Related to

- Usual curvature:

$$R_P(X, Y)Z = R(P(X), P(Y))Z + \nabla_{N_P(X, Y)}Z$$

- Usual torsion:

$$\begin{aligned}\tau_P(X, Y) &= T(P(X), P(Y)) + N_P(X, Y) \\ &\quad - \frac{1}{2}[(D_X K)Y - (D_Y K)X]\end{aligned}$$

Jacobi identity

$$\begin{aligned}
J^D(X, Y, Z, W) = & \\
& R_P(X, Y, Z, W) + R_P(Y, Z, X, W) + R_P(Z, X, Y, W) \\
& - R_P(W, Z, X, Y) - R_P(W, X, Y, Z) - R_P(W, Y, Z, X) \\
& - \eta(W, \nabla_{\tau_P(X, Y)} Z) - \eta(W, \nabla_{\tau_P(Y, Z)} X) - \eta(W, \nabla_{\tau_P(Z, X)} Y) \\
& - \eta(Z, \nabla_{\tau_P(X, W)} Y) - \eta(X, \nabla_{\tau_P(Y, W)} Z) + \eta(Y, \nabla_{\tau_P(W, Z)} X) \\
& + \eta(\theta_D(Z, X), \theta_D(W, Y)) - \eta(\theta_D(Z, Y), \theta_D(W, X)) \\
& - \eta(\theta_D(Y, X), \theta_D(W, Z))
\end{aligned}$$

Jacobi identity

Three contributions: curvature, torsion, twist θ_D

- ▶ L, \tilde{L} Lagrangian $\Rightarrow P(\theta_D) = 0 \Rightarrow \eta(\theta_D, \theta_D) = 0$
- ▶ Integrability of L = anchoring of $P \Rightarrow \tau_P = 0$
- ▶ Check R_P individually

Canonical Connections

Para-Kähler

Levi-Civita connection $\overset{\circ}{\nabla}$ of η

- ▶ symplectic form is closed: $d\omega = 0$
- ▶ bi-Lagrangian structure is integrable: $N_K = 0$
- ▶ then $\overset{\circ}{\nabla}\eta = 0$ and $\overset{\circ}{\nabla}\omega = 0$

Generalized Lie derivative

- ▶ projected derivative $\overset{\circ}{D}_X = \overset{\circ}{\nabla}_{P(X)}$
- ▶ generalized Lie derivative $\mathbf{L}_X^{\overset{\circ}{D}}$ with $J^{\overset{\circ}{D}} = 0$
- ▶ since $\overset{\circ}{R}_P = 0$ and $\overset{\circ}{\tau}_P = 0$

Para-Kähler

For DFT on para-Kähler manifold $(\mathcal{P}, \eta, \omega)$:
 $\mathbf{L}_X^{\mathring{D}}$ is a generalized Lie derivative that satisfies the Jacobi identity for arbitrary metric η

But does not work if $d\omega \neq 0$ — can we do better?

Para-Hermitian

Canonical para-Hermitian connection ∇^c

- ▶ relax closure condition: $d\omega \neq 0$
- ▶ but still integrable: $N_K = 0$
- ▶ introduce

$$\nabla_X^c = P\overset{\circ}{\nabla}_X P + \tilde{P}\overset{\circ}{\nabla}_X \tilde{P}$$

- ▶ given by contorsion

$$\eta(\nabla_X^c Y, Z) = \eta(\overset{\circ}{\nabla}_X Y, Z) - \frac{1}{2}\overset{\circ}{\nabla}_X \omega(Y, K(Z))$$

Para-Hermitian

Properties

- ▶ compatible with η and ω : $\nabla^c \eta = 0$ and $\nabla^c \omega = 0$
- ▶ compatible with K : $\nabla^c K = K \nabla^c$
- ▶ generalized torsion

$$\mathcal{T}^c(X, Y, Z) = \frac{1}{2} d\omega(K(X), K(Y), K(Z)) - \frac{1}{4} \sum_{cycl.} N_K(X, Y, Z)$$

defined as

$$\mathcal{T}(X, Y, Z) := \eta(\mathbf{L}_X^\nabla Y - \mathbf{L}_X^{\dot{\nabla}} Y, Z) = \sum_{cycl.} \Omega(X, Y, Z)$$

Para-Hermitian

Generalized Lie derivative

- ▶ projected derivative $D_X^c = \nabla_{P(X)}^c$
- ▶ generalized Lie derivative $\mathbf{L}_X^{D^c}$ with $J^{D^c} = 0$
- ▶ since R_P^c terms in J^c vanish by Bianchi identity for \mathring{R}
- ▶ projected torsion: $\tau_P^c = \mathring{\tau}_P = 0$

Para-Hermitian

For DFT on para-Hermitian manifold $(\mathcal{P}, \eta, \omega)$:
 $\mathbf{L}_X^{\text{D}^c}$ is a generalized Lie derivative that satisfies the Jacobi identity for arbitrary metric η

Relation to Generalized Geometry

Relation to Generalized Geometry

Invertible map $\rho : TM \oplus T^*M \rightarrow T\mathcal{P}|_M$

$$\rho : (x, \alpha) \mapsto x + \eta^{-1}(\alpha) := x + \tilde{x} = X$$

$$\rho^{-1} : X \mapsto (P(X), \eta(\tilde{P}(X)))$$

where M is a leaf of the foliation \mathcal{F} of $\mathcal{P} \rightarrow \rho$ can be extended to all of $T\mathcal{P}$

Relation to Generalized Geometry

Translate $\mathbb{L}_{(x,\alpha)} = ([x, y], \mathcal{L}_x\beta - \iota_y d\alpha)$ to some $\mathbf{L}_X Y$

$$\mathbb{L}_{\rho(x,\alpha)}\rho(y, \beta) = [x, y] + \eta^{-1}(\mathcal{L}_x\beta - \iota_y d\alpha) = \mathbf{L}_X Y$$

Can rewrite this as (using $x = P(X)$, $\tilde{x} = \tilde{P}(X)$, etc.)

$$\eta(\mathbf{L}_X Y, Z) = \eta(\nabla_{P(X)}^c Y - \nabla_{P(Y)}^c X, Z) + \eta(\nabla_{P(Z)}^c X, Y)$$

$$\mathbf{L}_X^{\text{D}^c} Y = \mathbb{L}_{\rho(x,\alpha)}\rho(y, \beta)$$

Relation to Generalized Geometry

Presence of symplectic structure ω gives map ρ

- ▶ ρ maps $\mathbb{L}_{(x,\alpha)}$ of GG to generalized Lie derivative $\mathbf{L}_X^{\text{D}^c}$ of Leibniz algebroid $(T\mathcal{P}, \eta, P, \mathbf{L}^{\text{D}^c})$
- ▶ Yields canonical connection ∇^c
- ▶ Alternative proof of Jacobi identity for $\mathbf{L}_X^{\text{D}^c}$
- ▶ Specifies relation between GG and DFT:
spacetime M is leaf of foliation \mathcal{F} with tangent $L = \text{Im } P$

Outlook

- ▶ Include generalized metric \mathcal{H}
- ▶ Relate to “Born connection” (compatible with $(\eta, \omega, \mathcal{H})$)
- ▶ Relax integrability constraints

Summary

- ▶ Close algebra by using projected derivatives instead of section condition
- ▶ DFT lives on a para-Hermitian manifold – includes a symplectic structure ω
- ▶ Canonical connection and its generalized Lie derivative satisfy Jacobi identity

String Theory

Tseytlin Action on phase space with $X = (x/\lambda, y/\epsilon)$

$$S = \frac{1}{2} \int d\tau d\sigma [(\eta_{AB} + \omega_{AB}) \partial_\tau X^A \partial_\sigma X^B - \mathcal{H}_{AB} \partial_\sigma X^A \partial_\sigma X^B]$$

- ▶ including topological term

[Giveon, Rocek; Hull]

String Theory

- ▶ chiral structure: $J = \eta^{-1} \mathcal{H}$
- ▶ T-duality on target space: $X \rightarrow J(X)$
- ▶ ω and K not required, but present

Para-quaternionic Manifold

Born Geometry $(\mathcal{P}; \eta, \omega, \mathcal{H}) \longrightarrow$ para-quaternions (I, J, K)

- ▶ complex structure $I = \mathcal{H}^{-1}\omega$ ($I^2 = -1$)
- ▶ chiral structure $J = \eta^{-1}\mathcal{H}$ ($J^2 = +1$)
- ▶ real structure $K = \eta^{-1}\omega$ ($K^2 = +1$)

All mutually anti-commute

$$\begin{aligned} I &= JK = -KJ, \\ J &= IK = -KI, \\ K &= JI = -IJ, \end{aligned} \qquad IJK = -1$$

The Nijenhuis Tensor

The Nijenhuis Tensor of a tangent bundle structure A

$$N_A \in \Gamma(\Lambda^2(\mathcal{P}) \otimes \mathfrak{X}(\mathcal{P}))$$

$$N_A(X, Y) = A([A(X), Y] + [X, A(Y)]) - [A(X), A(Y)] - A^2[X, Y]$$

If A is integrable, $N_A = 0$.

The Nijenhuis Tensor

For bi-Lagrangian structure $K = \eta^{-1}\omega$

$$\begin{aligned} N_K(X, Y, Z) &= \overset{\circ}{\nabla}_Y \omega(X, K(Z)) - \overset{\circ}{\nabla}_X \omega(Y, K(Z)) \\ &\quad + \overset{\circ}{\nabla}_{K(Y)} \omega(X, Z) - \overset{\circ}{\nabla}_{K(X)} \omega(Y, Z) \\ &= d\omega(K(X), K(Y), K(Z)) + d\omega(X, Y, K(Z)) \\ &\quad + 2\overset{\circ}{\nabla}_{K(Z)} \omega(X, Y) \end{aligned}$$