

Supersymmetric Backgrounds and Generalised Holonomy

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Recent Advances in T/U-dualities and Generalized Geometries
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[1411.5721](#) with André Coimbra and Daniel Waldram
and [1504.02465](#) & [1606.09304](#) with André Coimbra

Introduction

Minkowski backgrounds : $M^{D-1,1} \times_w M_{int}$

▶ No fluxes $\rightarrow \nabla\epsilon = 0$

\rightarrow Special holonomy! E.g. CY_3 , G_2 holonomy, etc.

\rightarrow Integrable!

[Candelas, Horowitz, Strominger & Witten '85]

▶ Fluxes $\rightarrow \nabla\epsilon = (\text{"Flux"}) \cdot \epsilon \neq 0$

[Strominger '86, Hull '86]

\rightarrow G structure

[Gauntlett, Martelli, Pakis & Waldram '02]

\rightarrow intrinsic torsion

▶ Generalised Geometry on $T \oplus T^*$ includes H flux!

\rightarrow Generalised Calabi-Yau $d_H\Phi^\pm = 0$

\rightarrow Integrable! (If no RR) [Graña, Minasian, Petrini & Tomasiello '04]

▶ Integrable structure \forall fluxes? Generalised special holonomy?

Outline of talk

- ▶ Review: 4d SUSY Minkowski backgrounds of 11d sugra
- ▶ Review: G structures and intrinsic torsion
→ Apply to SUSY backgrounds
- ▶ $E_{d(d)} \times \mathbb{R}^+$ Generalised Geometry
- ▶ $\mathcal{N} \leq 2$ SUSY backgrounds \leftrightarrow Generalised Special Holonomy
- ▶ $\mathcal{N} \geq 3$ SUSY backgrounds \leftrightarrow Generalised Special Holonomy
- ▶ Killing superalgebra

- ▶ Field content $\{g_{\mu\nu}, \mathcal{A}_{\mu\nu\rho}, \psi_\mu\}$ with $\mathcal{F}_4 = d\mathcal{A}_3$

- ▶ Bosonic Action

$$S_B \sim \int (\text{vol}_g \mathcal{R} - \frac{1}{2} \mathcal{F} \wedge * \mathcal{F} - \frac{1}{6} \mathcal{A} \wedge \mathcal{F} \wedge \mathcal{F})$$

- ▶ Supersymmetry

$$\delta\psi_\mu = \nabla_\mu \varepsilon + \frac{1}{288} (\Gamma_\mu^{\nu_1 \dots \nu_4} - 8\delta_\mu^{\nu_1} \Gamma^{\nu_2 \nu_3 \nu_4}) \mathcal{F}_{\nu_1 \dots \nu_4} \varepsilon$$

Remark:

Could examine holonomy of $\tilde{D}_\mu \varepsilon = \uparrow$ [Duff & Stelle '91; Duff & Liu '03; Hull '03]

We take different approach...

Restricting to 7 dimensions

- ▶ Warped metric ansatz ($\mu, \nu = 0, \dots, 3$) ($m, n = 1, \dots, 7$)

$$ds_{11}^2 = e^{2\Delta(x)} \eta_{\mu\nu} dy^\mu dy^\nu + g_{mn}(x) dx^m dx^n$$

- ▶ Internal fields: $\{g_{mn}, A_{mnp}, \tilde{A}_{m_1 \dots m_6}, \Delta; \psi_m, \rho\}$

- ▶ Field strengths

$$F_4 = dA_3 \qquad \tilde{F}_7 = d\tilde{A}_6 - \frac{1}{2} A_3 \wedge F_4,$$

- ▶ Gauge transformation: ($\Lambda \in \Lambda^2 T^* M$, $\tilde{\Lambda} \in \Lambda^5 T^* M$)

$$A' = A + d\Lambda \qquad \tilde{A}' = \tilde{A} + d\tilde{\Lambda} - \frac{1}{2} d\Lambda \wedge A$$

Restricting to 7 dimensions

- ▶ Spinor decomposition

$$\varepsilon = \eta_+ \otimes \epsilon + \eta_- \otimes \epsilon^c$$

- ▶ Internal SUSY variations / Killing spinor equations

$$\begin{aligned} \delta\psi_m &= \nabla_m \epsilon + \frac{1}{288} (\gamma_m{}^{n_1 \dots n_4} - 8\delta_m{}^{n_1} \gamma^{n_2 n_3 n_4}) F_{n_1 \dots n_4} \epsilon \\ &\quad - \frac{1}{12} \frac{1}{6!} \tilde{F}_{mn_1 \dots n_6} \gamma^{n_1 \dots n_6} \epsilon = 0 \end{aligned}$$

$$\delta\rho = \not{\nabla} \epsilon + (\not{\partial} \Delta) \epsilon - \frac{1}{4} \not{F} \epsilon - \frac{1}{4} \not{\tilde{F}} \epsilon = 0$$

- ▶ $\mathcal{N} = N$ SUSY background iff

$\exists N$ independent **non-vanishing complex** ϵ satisfying \uparrow

Definition:

G -structure \equiv covering with local frames related by G

E.g. Orthonormal frames $g(\hat{e}_a, \hat{e}_b) = \delta_{ab}$

$\hat{e}'_a = \Lambda_a{}^b \hat{e}_b$ with $\Lambda \in SO(d)$ \rightarrow $SO(d)$ structure

E.g. real spinor ϵ in 7d \rightarrow Stabiliser $G_2 \subset spin(7)$

\rightarrow frames \hat{e}_a with $\epsilon \propto (1, 0, \dots, 0)$ \rightarrow G_2 structure

Intrinsic Torsion

- ▶ Given $\hat{\nabla}^{\mathfrak{g}}\epsilon = 0$, any G -connection can be written

$$\nabla^{\mathfrak{g}} = \hat{\nabla}^{\mathfrak{g}} + \Omega \quad \Omega \in T^* \otimes \mathfrak{g}$$

- ▶ Let $W = T \otimes \Lambda^2 T^* \sim \{\text{Torsions}\}$

- ▶ Torsion map on Ω :

$$\tau(\Omega) = T(\nabla^{\mathfrak{g}}) - T(\hat{\nabla}^{\mathfrak{g}})$$

- ▶ G -structure defines section of $W/\text{Im}(\tau) \rightarrow$ **Intrinsic torsion!**

$\exists G$ -compatible torsion-free $\nabla^{\mathfrak{g}} \Leftrightarrow$ Intrinsic torsion vanishes

\Leftrightarrow Special holonomy G

Intrinsic Torsion

Set: $\nabla^{\mathfrak{g}} = \nabla^{\text{LC}} + \Sigma \quad \Sigma \in T^* \otimes \mathfrak{so}(d)$

Intrinsic torsion \equiv some (G irreducible) parts of Σ

Which?

\rightarrow Calculate $W/\text{Im}(\tau)$ by linear algebra

Intrinsic Torsion

Appears via:

- ▶ Φ an invariant tensor of G
- ▶ Operator \mathcal{D} such that $\mathcal{D}^{(\nabla)}$ sees only $T(\nabla) = 0$
- ▶ Then $\mathcal{D}\Phi = \mathcal{D}^{(\nabla^{\text{LC}})} = \mathcal{D}^{(\nabla^{\text{g}} - \Sigma)}\Phi = -\tau^{\text{int}}(\Sigma) \circ \Phi$
→ linear dependence on intrinsic torsion.

Example:

- ▶ Form bilinear $\Phi_{(k)} \sim \epsilon \gamma_{m_1 \dots m_k} \epsilon$
- ▶ $\mathcal{D} = d$ $(\nabla_{[m} \omega_{n_1 \dots n_k]} = \partial_{[m} \omega_{n_1 \dots n_k]} - T_{[m}^p{}_{n_1} \omega_{|p|n_2 \dots n_k]})$
- ▶ $\Rightarrow d\Phi_{(k)}$ is part of intrinsic torsion.

G-structures and SUSY backgrounds

- ▶ $\epsilon = \epsilon_1 + i\epsilon_2$ stabilised by $\begin{cases} G_2 & \epsilon_1 \propto \epsilon_2 \\ SU(3) & \text{otherwise} \end{cases}$
- ▶ So ϵ defines local G_2 or $SU(3)$ structure
- ▶ Form bilinears $\Phi_k \sim \epsilon \gamma_{m_1 \dots m_k} \epsilon$
- ▶ Find: **intrinsic torsion** \sim Flux

$$\nabla \epsilon = (\text{"Flux"}) \cdot \epsilon \quad \Rightarrow \quad d\Phi_k \sim \text{"Flux"}$$

[Gauntlett, Martelli, Pakis & Waldram '02] [Cardoso, Curio, Dall'Agata, Lüst, Manousselis & Zoupanos '02]
[Kaste, Minasian & Tomasiello '03] [Lukas & Saffin '04]

- ▶ Consider a bundle

$$E \simeq TM_7 \oplus \Lambda^2 T^* M_7 \oplus \Lambda^5 T^* M_7 \oplus (T^* M_7 \otimes \Lambda^7 T^* M_7)$$

- ▶ Sections of $E \leftrightarrow$ infinitesimal **diffeos** + **gauge** transformations
- ▶ Carries action of $E_{7(7)} \times \mathbb{R}^+$ in **56**₊₁ representation
- ▶ Dorfman derivative:

$$\begin{aligned} L_V &= \partial_V - (\partial \times_{\text{ad}} V) \cdot \\ &\sim \mathcal{L}_v + (d\Lambda_{(2)} \cdot) + (d\tilde{\Lambda}_{(5)} \cdot) \end{aligned}$$

- ▶ **Connection:** For $\Omega_M \in \text{ad}(E_{7(7)} \times \mathbb{R}^+)$

$$D : E \rightarrow E^* \otimes E$$

$$D_M V^A = \partial_M V^A + \Omega_M^A{}_B V^B$$

- ▶ **Torsion:** Define $T(V) \in \text{ad}(E_{7(7)} \times \mathbb{R}^+)$

$$T(V) \cdot = L_V^{(\partial \rightarrow D)} - L_V$$

- ▶ For a **torsion-free** connection D

$$L_V = \partial_V - (\partial \times_{\text{ad}} V) \cdot = D_V - (D \times_{\text{ad}} V) \cdot$$

Supergravity Fields and the Generalised Metric

- ▶ Can build generalised metric

$$G \sim \{g_{mn}, A_{mnp}, \tilde{A}_{m_1 \dots m_6}, \Delta\} \in \frac{E_{7(7)} \times \mathbb{R}^+}{SU(8)}$$

→ Defines $SU(8)$ structure on E

- ▶ Supergravity fermions → $SU(8)$ representations

$$\epsilon^\alpha \in \mathbf{8} \quad \rho_\alpha \in \bar{\mathbf{8}} \quad \psi^{[\alpha\beta\gamma]} \in \mathbf{56}$$

- ▶ Generalised vector in $SU(8)$ indices

$$\mathbf{56} \rightarrow \mathbf{28} + \bar{\mathbf{28}} \quad V = (V^{[\alpha\beta]}, \bar{V}_{[\alpha\beta]})$$

- ▶ $SU(8)$ (metric) compatible connection defined by

$$DG = 0$$

- ▶ \exists family of D torsion-free & compatible (Not unique!!!)

- ▶ $T = 0 \Rightarrow$ Some cpts fixed to be $\nabla, F, \tilde{F}, d\Delta$

- ▶ SUSY variations are:

$$\delta\rho_\alpha = \bar{D}_{\alpha\beta}\epsilon^\beta \qquad \delta\psi^{[\alpha\beta\gamma]} = D^{[\alpha\beta}\epsilon^{\gamma]}$$

- ▶ These operators are **unique!**

- ▶ Write them collectively as $(\delta\psi, \delta\rho) = D \times_{\text{SUSY}} \epsilon$

Generalised Intrinsic Torsion

Set:
$$D^{\mathfrak{g}} = D^{\text{LC}} + \Sigma \quad \Sigma \in E^* \otimes \mathfrak{su}(8)$$

Generalised Intrinsic torsion \equiv some (G irreducible) parts of Σ

Which?

→ Calculate $W/\text{Im}(\tau)$ by linear algebra

Or look at:

→ Unique operators \mathcal{D} acting on G -invariant tensors Φ

$$\mathcal{D}\Phi = -\tau^{\text{int}}(\Sigma) \cdot \Phi$$

- ▶ ϵ defines (global) $SU(7)$ structure on E

Key result:

Killing spinor eqns $(D \times_{\text{SUSY}} \epsilon) \equiv SU(7)$ Intrinsic torsion

- ▶ I.e SUSY \Rightarrow $SU(7)$ structure has vanishing intrinsic torsion
- ▶ Analogue of spaces with special holonomy
- ▶ $SU(7)$ “generalised holonomy”

$\mathcal{N} = 1$ Minkowski background $\Leftrightarrow SU(7)$ **generalised holonomy**

Comment:

▶ $D^{[\alpha\beta}\epsilon^{\gamma]} = 0$ and $\bar{D}_{\alpha\beta}\epsilon^{\beta} = 0$ (SUSY)

\Rightarrow Generalised **Ricci flat** (Eqns of motion)

- ▶ $\mathcal{N} = 1$ AdS backgrounds

$$D^{[\alpha\beta}\epsilon^{\gamma]} = 0 \qquad D_{\alpha\beta}\epsilon^{\beta} = \Lambda\bar{\epsilon}_{\alpha}$$

$\Lambda \rightarrow$ (generalised) singlet torsion

- ▶ “Weak generalised holonomy”
[c.f. Sasaki-Einstein, weak G_2 etc.]
- ▶ SUSY \Rightarrow Generalised Einstein

$$R_{MN} \sim \Lambda^2 G_{MN}$$

Extension : Higher \mathcal{N} backgrounds?

Would like that:

$\mathcal{N} = N$ Minkowski background $\stackrel{?}{\Leftrightarrow} SU(8 - N)$ generalised holonomy

- ▶ $\mathcal{N} = 2 \rightarrow$ torsion-free $SU(6)$ structure

(same proof: $(D \times_{\text{SUSY}} \epsilon_{1,2}) \equiv$ Intrinsic torsion)

(Also $\mathcal{N} = 2$ AdS [Ashmore, Petrini & Waldram '16])

- ▶ $\mathcal{N} \geq 3$ more difficult: $(D \times_{\text{SUSY}} \epsilon_i) \not\equiv$ Intrinsic torsion

\rightarrow What happens then?...

- ▶ Basis ϵ_i for $i = 1, \dots, N$ of \mathbb{C} -vector space of Killing spinors
- ▶ SUSY \Rightarrow rescaled $\hat{\epsilon}_i = e^{-\Delta/2} \epsilon_i$ satisfies

$$\tilde{\nabla}_m \hat{\epsilon} = \nabla_m \hat{\epsilon} - \frac{1}{4} \frac{1}{3!} F_{mnpq} \gamma^{npq} \hat{\epsilon} - \frac{1}{4} \frac{1}{6!} \tilde{F}_{mn_1 \dots n_6} \gamma^{n_1 \dots n_6} \hat{\epsilon} = 0$$

- ▶ $\{\gamma^{(2)}, \gamma^{(3)}, \gamma^{(6)}\}$ generate $SU(8)$ so $SU(8)$ connection!
- ▶ \Rightarrow preserves inner products $\hat{\epsilon}_i^\dagger \hat{\epsilon}_j$

- ▶ So \exists unitary basis $\hat{\epsilon}_i^\dagger \hat{\epsilon}_j = \delta_{ij}$

$SU(8 - N)$ Intrinsic torsion

- ▶ Split $SU(8)$ index : $\alpha = (i, a)$, where $i \leftrightarrow$ Killing spinors.
- ▶ Let $D^{\mathfrak{g}} = D^{\text{LC}} + \Sigma$ where
 - ▶ $D^{\mathfrak{g}}$ an $SU(8 - N)$ connection $D\epsilon_i = 0$
 - ▶ D^{LC} a torsion-free $SU(8)$ connection
 - ▶ $\Sigma = (\Sigma_{[\alpha\beta]}^{\gamma\delta}, \Sigma^{[\alpha\beta]\gamma\delta}) \in E^* \otimes \text{ad } SU(8)$ ← torsion is here!
- ▶ $SU(8 - N)$ intrinsic torsion

$$\hat{\tau}_{\text{int}} = (\Sigma_{\alpha\gamma}^{\gamma i}, \Sigma_{[\alpha\beta]}^i{}_{\gamma}, \Sigma_{[ij}^a{}_{k]}) + (\text{c.c.})$$

$SU(8 - N)$ Intrinsic torsion vs SUSY

- ▶ $SU(8 - N)$ intrinsic torsion

$$\hat{\tau}_{\text{int}} = (\Sigma_{\alpha\gamma}{}^{\gamma}{}_i, \Sigma_{[\alpha\beta}{}^i{}_{\gamma]}, \Sigma_{[ij}{}^a{}_{k]}) + (\text{c.c.})$$

- ▶ Supersymmetry operators are

$$D_{[\alpha\beta}^{\text{LC}} \bar{\epsilon}_{\gamma]}^i = -\Sigma_{[\alpha\beta}{}^i{}_{\gamma]} \quad D_{\alpha\beta}^{\text{LC}} \epsilon_i^{\beta} = -\Sigma_{\alpha\gamma}{}^{\gamma}{}_i$$

- ▶ $\Sigma_{[ij}{}^a{}_{k]}$ does not appear!
- ▶ Looks impossible that SUSY could $\Rightarrow \hat{\tau}_{\text{int}} = 0$
- ▶ For $\mathcal{N} \leq 2$ have $\Sigma_{[ij}{}^a{}_{k]} = 0$ so matches

Killing vectors

Killing vectors have

$$\mathcal{L}_v g = 0 \quad \Leftrightarrow \quad \nabla_{(m} v_n) = 0 \quad \Leftrightarrow \quad \nabla_m v_n = \nabla_{[m} v_{n]}$$

- ▶ So $(\nabla v) \in \text{ad}(SO(d)) \subset \text{ad}(GL(d, \mathbb{R}))$
- ▶ So ∇ and (∇v) can act on arbitrary $Spin(d)$ objects
- ▶ \rightarrow Kosmann's spinorial Lie derivative

$$\mathcal{L}_v^K \epsilon = \nabla_v \epsilon + \frac{1}{4} (\nabla_{[a} v_{b]}) \gamma^{ab} \epsilon$$

- ▶ “Agrees” with Lie derivative if v a Killing vector!

$$\mathcal{L}_v = \nabla_v - (\nabla \times_{\text{ad } GL(d, \mathbb{R})} v) \cdot = \nabla_v - (\nabla \times_{\text{ad } SO(d)} v) \cdot$$

Generalised Killing vectors (GKVs) have

$$L_V G = 0 \quad \Leftrightarrow \quad D \times_{\text{ad}(E_{7(7)} \times \mathbb{R}^+)} V = D \times_{\text{ad}(SU(8))} V$$

\Rightarrow Dorfman derivative can naturally act on $SU(8)$ objects!

$$L_V = D_V - (D \times_{\text{ad}(E_{7(7)} \times \mathbb{R}^+)} V) \cdot = D_V - (D \times_{\text{ad}(SU(8))} V) \cdot$$

Comment:

Vector part $V = v + \dots$ is flux-preserving **isometry**

$$\mathcal{L}_v g = \mathcal{L}_v \Delta = \mathcal{L}_v F = \mathcal{L}_v \tilde{F} = 0$$

Kosmann-Dorfman (KD) derivative

Define:

$$L_V = D_V - (D \times_{\text{ad}(SU(8))} V).$$

For **GKVs**:

- ▶ “Agrees” with Dorfman derivative
- ▶ Algebra closes: $[L_V, L_{V'}] = L_{L_V V'}$
- ▶ Commutes with SUSY operators

$$L_V(D \times_{\text{SUSY}} \epsilon) = D \times_{\text{SUSY}} (L_V \epsilon)$$

-) \Rightarrow For V a GKV

$$D \times_{\text{SUSY}} \epsilon = 0 \quad \Rightarrow \quad D \times_{\text{SUSY}} (L_V \epsilon) = 0$$

-) { Killing spinors } \sim representation of isometry group
-) \Rightarrow If V a GKV then \exists constant matrix X_i^j s.t.

$$L_V \epsilon_i = X_i^j \epsilon_j$$

Spinor bilinears and trilinears

Complex generalised vectors V_{ij} and $W^{ij} = (V_{ij})^*$

$$(V_{ij})^{\alpha\beta} = \epsilon_i^{[\alpha} \epsilon_j^{\beta]} \quad (V_{ij})_{\alpha\beta} = 0$$

SUSY \Rightarrow GKV's

$$(D \times_{\text{ad}(SU(8))^\perp} V = 0)$$

$$D^{[\alpha\beta}(\epsilon_i^\gamma \epsilon_j^{\delta]}) = 0,$$

$$D_{\alpha\beta}(\epsilon_i^{[\alpha} \epsilon_j^{\beta]}) = 0,$$

$\Rightarrow \exists$ constants $X_{ijk}{}^l$ s.t.

$$\boxed{L_{V_{ij}} \epsilon_k = X_{ijk}{}^l \epsilon_l}$$

\rightarrow Closure of some algebra?

See later...

Find (using SUSY and $\epsilon_i^\dagger \epsilon_j = \delta_{ij}$):

$$\boxed{L_{V_{ij}} \epsilon_k = D_{V_{[ij}} \epsilon_k]} \quad L_{W^{ij}} \epsilon_k = 0$$

Then “closure” (and $\epsilon_i^\dagger \epsilon_j = \delta_{ij}$)

$$\Rightarrow \boxed{L_{V_{ij}} \epsilon_k = 0 \quad L_{W^{ij}} \epsilon_k = 0}$$

GKVs preserving the Killing spinors!

$SU(8 - N)$ Intrinsic torsion revisited

Return to setup $D^{SU(8-N)} = \hat{D}^{LC} + \Sigma$ from before

We have that:

$$(L_{V_{ij}} \epsilon_k)^a \sim \epsilon_{[i}^{\gamma} \epsilon_{j]}^{\gamma'} (\bar{D}_{|\gamma\gamma'|} \epsilon_k^a) \sim \Sigma_{[ij]^a k}$$

This was the missing component of the **intrinsic torsion**!

Further: showed that SUSY $\Rightarrow L_{V_{ij}} \epsilon_k = 0$, so **it vanishes**!

Generalised special holonomy!!!

Result:

$$\mathcal{N} = N \text{ Minkowski background} \Leftrightarrow SU(8 - N) \text{ generalised holonomy}$$

In other dimensions:

d	\tilde{H}_d	Generalised Holonomy
7	$SU(8)$	$SU(8 - \mathcal{N})$
6	$Sp(8)$	$Sp(8 - 2\mathcal{N})$
5	$Sp(4) \times Sp(4)$	$Sp(4 - 2\mathcal{N}_+) \times Sp(4 - 2\mathcal{N}_-)$
4	$Sp(4)$	$Sp(4 - 2\mathcal{N})$

Also for type IIA and IIB

Internal Killing superalgebra

Reminiscent of “superalgebra”

$$\begin{aligned} [\epsilon_i, \epsilon_j] &= V_{ij} & [Q, Q] &= P \\ [V_{ij}, \epsilon_k] &= L_{V_{ij}} \epsilon_k = 0 & [P, Q] &= 0 \\ [V_{ii'}, V_{jj'}] &= L_{V_{ii'}} V_{jj'} = 0 & [P, P] &= 0 \end{aligned}$$

Not a coincidence – “internal sector” of [Killing superalgebra](#)

Lie Superalgebra on $\{ \text{Killing vectors} \} \oplus \{ \text{Killing spinors} \}$

$$[\varepsilon_1, \varepsilon_2] = v(\varepsilon_1, \varepsilon_2)$$

$$[v, \varepsilon] = \mathcal{L}_v \varepsilon$$

$$[v_1, v_2] = \mathcal{L}_{v_1} v_2$$

Algebra of “super-isometries”

11d Killing superalgebra (KSA)

Introduce basis of external Weyl spinors $\eta_1 = (1, 0)$, $\eta_2 = (0, 1)$

$$Q_{i,\alpha} = \eta_\alpha \otimes \epsilon_i, \quad \bar{Q}_i^{\dot{\alpha}} = \bar{\eta}^{\dot{\alpha}} \otimes \epsilon_i^c,$$

and internal (complex) vectors $z_{ij} = (\epsilon_i^c \gamma^m \epsilon_j) \frac{\partial}{\partial x^m}$

$$[Q_{i,\alpha}, \bar{Q}_{j,\dot{\beta}}] = \delta_{ij} (\sigma^\mu)_{\alpha\dot{\beta}} \frac{\partial}{\partial x^\mu},$$

$$[Q_{i,\alpha}, Q_{j,\beta}] = \epsilon_{\alpha\beta} z_{ij},$$

$$[\bar{Q}_{i,\dot{\alpha}}, \bar{Q}_{j,\dot{\beta}}] = \epsilon_{\dot{\alpha}\dot{\beta}} \bar{z}_{ij},$$

KSA \cong Supertranslational part of **super-Poincaré algebra**

Crucially: Internal isometries always central $[z_{ij}, \cdot] = 0$

Conclusions

Result:

$\mathcal{N} = N$ Minkowski background $\Leftrightarrow \mathcal{G}_N$ generalised holonomy

d	\tilde{H}_d	\mathcal{G}_N
7	$SU(8)$	$SU(8 - \mathcal{N})$
6	$Sp(8)$	$Sp(8 - 2\mathcal{N})$
5	$Sp(4) \times Sp(4)$	$Sp(4 - 2\mathcal{N}_+) \times Sp(4 - 2\mathcal{N}_-)$
4	$Sp(4)$	$Sp(4 - 2\mathcal{N})$

KSA \cong Supertranslational part of super-Poincaré algebra

(Central charges \simeq generalised Killing vectors)

Further extensions?

- ▶ $\mathcal{N} = N$ AdS? - works the same way!
- (but some subtleties) [work in progress]
- ▶ Definition of “generalised holonomy”?
- ▶ Moduli? [Garcia-Fernandez, Rubio & Tipler '15; Ashmore & Waldram '15]
[Ashmore, Petrini & Waldram '15; Ashmore, Gabella, Grana, Petrini & Waldram '16]
- ▶ Higher derivative corrections? [Garcia-Fernandez '13]
[Coimbra, Minasian, Triendl & Waldram '14]
- ▶ Non-geometric backgrounds? [Grana, Minasian, Petrini & Waldram '08]

The End

- ▶ Thanks for your attention!